

## Applied Mathematics 3B

## Assignment #3

7:30, 16 August 2011

**1.** Consider the observable

 $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$ 

Calculate the expectation value for a system described by the pure state  $(1,0)^T$ . Calculate the expectation value for a system described by the mixed state

 $\left(\begin{array}{cc} \frac{1}{2} & 0\\ 0 & \frac{1}{2} \end{array}\right).$ 

What can we conclude?

**2.** Consider the observable

Calculate the maximum expectation value M for a system described by a pure state  $\mathbf{x} \in \mathbb{C}^2$  and the pure state(s)  $\mathbf{x}$  at which the maximum is achieved. Let

 $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$ 

$$\rho := p\mathbf{x}\mathbf{x}^* + (1-p)\mathbf{y}\mathbf{y}^*$$

where  $p \in (0,1)$  and  $\mathbf{y} \in \mathbb{C}^2$  is linearly independent of  $\mathbf{x}$  determined above. Show that the expectation value for a system described by the mixed state  $\rho$  is less than M. Can this result be extended to all mixed states?

**3.** Consider the Hilbert space  $\mathbb{C}^4$ . Show that the matrix

$$\begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix}$$

describes an observable. Describe the measurement outcomes and associated probabilities when observing (performing the measurement on) a system described by the state

$$\frac{1}{\sqrt{2}} \begin{pmatrix} 1\\0\\0\\1 \end{pmatrix}.$$

What is the state after the measurement?

**4.** Let A and B be two commuting  $n \times n$  Hermitian matrices over  $\mathbb{C}$  each with distinct eigenvalues. Thus the corresponding eigenspaces are one-dimensional. Show that every eigenvector  $\mathbf{x}$  of A is also an eigenvector of B.

**Hint:** First show that  $B\mathbf{x}$  is either **0** or an eigenvector of A.

5. Find the constraints on pure states  $\mathbf{x}, \mathbf{y} \in \mathbb{C}^2$  for which, when classically mixed in equal proportions, we find the density matrix

$$\frac{1}{2}\mathbf{x}\mathbf{x}^* + \frac{1}{2}\mathbf{y}\mathbf{y}^* = \frac{1}{2}I_2.$$