

University of Johannesburg

Applied Mathematics 3B

Semester test 1

Solutions

1. We have

$$\begin{aligned} & \left[\frac{1}{4-2\sqrt{2}} \begin{pmatrix} 3-2\sqrt{2} & 1-\sqrt{2} \\ 1-\sqrt{2} & 1 \end{pmatrix} \right]^2 \\ &= \frac{1}{(4-2\sqrt{2})^2} \begin{pmatrix} (3-2\sqrt{2})^2 + (1-\sqrt{2})^2 & (3-2\sqrt{2})(1-\sqrt{2}) + (1-\sqrt{2}) \\ (3-2\sqrt{2})(1-\sqrt{2}) + (1-\sqrt{2}) & (1-\sqrt{2})^2 + 1 \end{pmatrix} \\ &= \frac{1}{(4-2\sqrt{2})^2} \begin{pmatrix} 20-14\sqrt{2} & (4-2\sqrt{2})(1-\sqrt{2}) \\ (4-2\sqrt{2})(1-\sqrt{2}) & 4-2\sqrt{2} \end{pmatrix} \\ &= \frac{1}{(4-2\sqrt{2})^2} \begin{pmatrix} (4-2\sqrt{2})(3-2\sqrt{2}) & (4-2\sqrt{2})(1-\sqrt{2}) \\ (4-2\sqrt{2})(1-\sqrt{2}) & 4-2\sqrt{2} \end{pmatrix} \\ &= \frac{1}{4-2\sqrt{2}} \begin{pmatrix} 3-2\sqrt{2} & 1-\sqrt{2} \\ 1-\sqrt{2} & 1 \end{pmatrix} \end{aligned}$$

where we used $(4-2\sqrt{2})(3-2\sqrt{2}) = 20-14\sqrt{2}$. The solution to the differential equation

$$\frac{d\psi}{dt} = \frac{i}{4-2\sqrt{2}} \begin{pmatrix} 3-2\sqrt{2} & 1-\sqrt{2} \\ 1-\sqrt{2} & 1 \end{pmatrix} \psi$$

is

$$\begin{aligned} \psi(t) &= \exp\left(\frac{it}{4-2\sqrt{2}} \begin{pmatrix} 3-2\sqrt{2} & 1-\sqrt{2} \\ 1-\sqrt{2} & 1 \end{pmatrix}\right) \psi(t=0) \\ &= \left(\sum_{j=0}^{\infty} \frac{(it)^j}{j!} \left[\frac{1}{4-2\sqrt{2}} \begin{pmatrix} 3-2\sqrt{2} & 1-\sqrt{2} \\ 1-\sqrt{2} & 1 \end{pmatrix}\right]^j\right) \psi(t=0) \\ &= \left(I_2 + \left(\sum_{j=1}^{\infty} \frac{(it)^j}{j!}\right) \left[\frac{1}{4-2\sqrt{2}} \begin{pmatrix} 3-2\sqrt{2} & 1-\sqrt{2} \\ 1-\sqrt{2} & 1 \end{pmatrix}\right]\right) \psi(t=0) \\ &= \left(I_2 + (e^{it} - 1) \left[\frac{1}{4-2\sqrt{2}} \begin{pmatrix} 3-2\sqrt{2} & 1-\sqrt{2} \\ 1-\sqrt{2} & 1 \end{pmatrix}\right]\right) \psi(t=0). \end{aligned}$$

At $t = \pi$ we find

$$\begin{aligned} \psi(t = \pi) &= \left(I_2 - 2 \left[\frac{1}{4-2\sqrt{2}} \begin{pmatrix} 3-2\sqrt{2} & 1-\sqrt{2} \\ 1-\sqrt{2} & 1 \end{pmatrix}\right]\right) \psi(t=0) \\ &= \frac{1}{2-\sqrt{2}} \begin{pmatrix} \sqrt{2}-1 & \sqrt{2}-1 \\ \sqrt{2}-1 & 1-\sqrt{2} \end{pmatrix} \psi(t=0) \\ &= \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \psi(t=0) \end{aligned}$$

i.e. we have performed the Hadamard transform. Thus we find

$$\begin{aligned} \psi(t=0) &= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \Rightarrow \psi(t=\pi) = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \\ \psi(t=0) &= \begin{pmatrix} 0 \\ 1 \end{pmatrix} \Rightarrow \psi(t=\pi) = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}. \end{aligned}$$

2. Since

$$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 1 \\ 0 & \sqrt{2} & 0 \\ 1 & 0 & -1 \end{pmatrix}^* = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 1 \\ 0 & \sqrt{2} & 0 \\ 1 & 0 & -1 \end{pmatrix}$$

the matrix describes an observable. It is straightforward to determine that the eigenvalues of

$$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 1 \\ 0 & \sqrt{2} & 0 \\ 1 & 0 & -1 \end{pmatrix}$$

are 1, 1 and -1 with corresponding orthonormal eigenvectors

$$\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \quad \frac{1}{\sqrt{4+2\sqrt{2}}} \begin{pmatrix} 1+\sqrt{2} \\ 0 \\ 1 \end{pmatrix}, \quad \frac{1}{\sqrt{4-2\sqrt{2}}} \begin{pmatrix} 1-\sqrt{2} \\ 0 \\ 1 \end{pmatrix}.$$

Thus we have the measurement outcome 1 with probability

$$\left| \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}^* \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right|^2 + \left| \frac{1}{\sqrt{4+2\sqrt{2}}} \begin{pmatrix} 1+\sqrt{2} \\ 0 \\ 1 \end{pmatrix}^* \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right|^2 = \frac{1}{3} + \frac{2+\sqrt{2}}{6} = \frac{2}{3} + \frac{\sqrt{2}}{6}$$

and the outcome -1 with probability

$$\left| \frac{1}{\sqrt{4-2\sqrt{2}}} \begin{pmatrix} 1-\sqrt{2} \\ 0 \\ 1 \end{pmatrix}^* \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right|^2 = \frac{1}{3} + \frac{2-\sqrt{2}}{6} = \frac{2}{3} - \frac{\sqrt{2}}{6}.$$

The corresponding projections are

$$\Pi_1 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}^* + \frac{1}{4+2\sqrt{2}} \begin{pmatrix} 1+\sqrt{2} \\ 0 \\ 1 \end{pmatrix} \begin{pmatrix} 1+\sqrt{2} \\ 0 \\ 1 \end{pmatrix}^* = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} + \frac{1}{4+2\sqrt{2}} \begin{pmatrix} 3+2\sqrt{2} & 0 & 1+\sqrt{2} \\ 0 & 0 & 0 \\ 1+\sqrt{2} & 0 & 1 \end{pmatrix}$$

and

$$\Pi_{-1} = \frac{1}{4-2\sqrt{2}} \begin{pmatrix} 1-\sqrt{2} \\ 0 \\ 1 \end{pmatrix} \begin{pmatrix} 1-\sqrt{2} \\ 0 \\ 1 \end{pmatrix}^* = \frac{1}{4-2\sqrt{2}} \begin{pmatrix} 3-2\sqrt{2} & 0 & 1-\sqrt{2} \\ 0 & 0 & 0 \\ 1-\sqrt{2} & 0 & 1 \end{pmatrix}.$$

If the measurement outcome was 1 then the state after measurement is

$$\frac{\Pi_1 \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}}{\left\| \Pi_1 \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\|} = \sqrt{\frac{6+4\sqrt{2}}{16+11\sqrt{2}}} \begin{pmatrix} \frac{4+3\sqrt{2}}{4+2\sqrt{2}} \\ 1 \\ \frac{1}{2} \end{pmatrix}.$$

If the measurement outcome was -1 then the state after measurement is

$$\frac{\Pi_{-1} \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}}{\left\| \Pi_{-1} \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\|} = \sqrt{\frac{6-4\sqrt{2}}{10-7\sqrt{2}}} \begin{pmatrix} \frac{4-3\sqrt{2}}{4-2\sqrt{2}} \\ 0 \\ \frac{1}{2} \end{pmatrix}.$$

3. We have

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}^T \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 2 & 2 \\ 2 & 2 & 2 \\ 2 & 2 & 2 \end{pmatrix}$$

With eigenvalues 6, 0 and 0 and corresponding orthonormal eigenvectors

$$\frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \quad \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}, \quad \frac{1}{\sqrt{6}} \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}.$$

The singular values are $\sqrt{6}$, 0 and 0. Thus we have

$$V = \begin{pmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & -\frac{2}{\sqrt{6}} \end{pmatrix}, \quad \Sigma = \begin{pmatrix} \sqrt{6} & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad U = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix}.$$

The first column of U follows from the first columns of V

$$\frac{1}{\sqrt{6}} \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix},$$

and the second is chosen to be orthonormal to the first. It follows that

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \sqrt{6} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & -\frac{2}{\sqrt{6}} \end{pmatrix}^T.$$

The decomposition is obviously not unique, for example we can exchange the last two columns of V ,

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \sqrt{6} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & -\frac{2}{\sqrt{6}} & 0 \end{pmatrix}^T$$

or make a different choice for the second column of U

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \sqrt{6} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & -\frac{2}{\sqrt{6}} \end{pmatrix}^T$$

or both

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} \sqrt{6} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & -\frac{2}{\sqrt{6}} & 0 \end{pmatrix}^T$$

amongst other possibilities.

4. Let

$$A := \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}, \quad B := \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}, \quad C := \begin{pmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \end{pmatrix}, \quad D := \begin{pmatrix} d_{11} & d_{12} \\ d_{21} & d_{22} \end{pmatrix}$$

where $a_{ij}, b_{ij}, c_{ij}, d_{ij} \in \mathbb{C}$ for $i, j \in \{1, 2\}$. We find

$$A \otimes B = \begin{pmatrix} a_{11}b_{11} & a_{11}b_{12} & a_{12}b_{11} & a_{12}b_{12} \\ a_{11}b_{21} & a_{11}b_{22} & a_{12}b_{21} & a_{12}b_{22} \\ a_{21}b_{11} & a_{21}b_{12} & a_{22}b_{11} & a_{22}b_{12} \\ a_{21}b_{21} & a_{21}b_{22} & a_{22}b_{21} & a_{22}b_{22} \end{pmatrix}$$

and

$$\frac{1}{2} (I_2 \otimes I_2 + \sigma_x \otimes \sigma_x + \sigma_y \otimes \sigma_y + \sigma_z \otimes \sigma_z) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}.$$

Equating these two matrices yields $a_{11}b_{11} = 1$ and $a_{22}b_{22} = 1$ which imply $a_{11} \neq 0$ and $b_{11} \neq 0$. Consequently the equation $a_{11}b_{22} = 0$ cannot be satisfied. Thus no such A and B can be found.

From

$$C \otimes D = \begin{pmatrix} c_{11}d_{11} & c_{11}d_{12} & c_{12}d_{11} & c_{12}d_{12} \\ c_{11}d_{21} & c_{11}d_{22} & c_{12}d_{21} & c_{12}d_{22} \\ c_{21}d_{11} & c_{21}d_{12} & c_{22}d_{11} & c_{22}d_{12} \\ c_{21}d_{21} & c_{21}d_{22} & c_{22}d_{21} & c_{22}d_{22} \end{pmatrix}$$

and

$$a I_2 \otimes I_2 + b \sigma_x \otimes \sigma_x + c \sigma_y \otimes \sigma_y + d \sigma_z \otimes \sigma_z = \begin{pmatrix} a+d & 0 & 0 & b-c \\ 0 & a-d & b+c & 0 \\ 0 & b+c & a-d & 0 \\ b-c & 0 & 0 & a+d \end{pmatrix},$$

where a_{11} and a are independent of each other, we find that

$$C \otimes D = a I_2 \otimes I_2 + b \sigma_x \otimes \sigma_x + c \sigma_y \otimes \sigma_y + d \sigma_z \otimes \sigma_z$$

leads to the equations

$$\begin{aligned} c_{11}d_{11} &= a+d & c_{11}d_{12} &= 0 & c_{12}d_{11} &= 0 & c_{12}d_{12} &= b-c \\ c_{11}d_{21} &= 0 & c_{11}d_{22} &= a-d & c_{12}d_{21} &= b+c & c_{12}d_{22} &= 0 \\ c_{21}d_{11} &= 0 & c_{21}d_{12} &= b+c & c_{22}d_{11} &= a-d & c_{22}d_{12} &= 0 \\ c_{21}d_{21} &= b-c & c_{21}d_{22} &= 0 & c_{22}d_{21} &= 0 & c_{22}d_{22} &= a+d \end{aligned}$$

The existence of solutions depends on the choice of C and D . In the following we assume $C \neq 0_2$ and $D \neq 0_2$ since $C = 0_2$ trivially provides the solution $a = b = c = d = 0$ (similarly for $D = 0_2$). This possibility will be incorporated in the final solutions.

A solution exists provided

$$\begin{pmatrix} c_{11} & 0 \\ 0 & c_{22} \end{pmatrix} \otimes \begin{pmatrix} 0 & d_{12} \\ d_{21} & 0 \end{pmatrix} = \begin{pmatrix} 0 & c_{12} \\ c_{21} & 0 \end{pmatrix} \otimes \begin{pmatrix} d_{11} & 0 \\ 0 & d_{22} \end{pmatrix} = 0_4$$

where 0_4 is the 4×4 zero matrix.

In other words C must be diagonal or have zeroes on the diagonal (similarly for D). Suppose C is non-zero and diagonal, then the above equation implies D is diagonal, $b = c = 0$ and

$$a = \frac{1}{2}c_{11}(d_{11} + d_{22}) = \frac{1}{2}c_{22}(d_{11} + d_{22}), \quad d = \frac{1}{2}c_{11}(d_{11} - d_{22}) = -\frac{1}{2}c_{22}(d_{11} - d_{22}).$$

For the above equalities to hold we must have $C = \alpha I_2$ and $D = \beta I_2$, or $C = \alpha \sigma_z$ and $D = \beta \sigma_z$ where $\alpha, \beta \in \mathbb{C}$ are arbitrary.

Similarly if C has zeroes on the diagonal, then D has zeroes on the diagonal, $a = d = 0$ and

$$b = \frac{1}{2}c_{12}(d_{12} + d_{21}) = \frac{1}{2}c_{21}(d_{12} + d_{21}), \quad c = \frac{1}{2}c_{12}(d_{21} - d_{12}) = -\frac{1}{2}c_{21}(d_{21} - d_{12}).$$

For the above equalities to hold we must have $C = \alpha \sigma_x$ and $D = \beta \sigma_x$, or $C = \alpha \sigma_y$ and $D = \beta \sigma_y$ where $\alpha, \beta \in \mathbb{C}$ are arbitrary.

To summarize

$$\begin{aligned} C = \alpha I_2, D = \beta I_2 &\Rightarrow a = \alpha\beta, b = c = d = 0 \\ C = \alpha \sigma_x, D = \beta \sigma_x &\Rightarrow b = \alpha\beta, a = c = d = 0 \\ C = \alpha \sigma_y, D = \beta \sigma_y &\Rightarrow c = \alpha\beta, a = b = d = 0 \\ C = \alpha \sigma_z, D = \beta \sigma_z &\Rightarrow d = \alpha\beta, a = b = c = 0 \end{aligned}$$

where $\alpha, \beta \in \mathbb{C}$ are arbitrary. For all other C and D no solution exists.